

L Number	Hits	Search Text	DB	Time stamp
-	598	701/300.ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/17 16:32
-	706	(road and window\$1) and gradient\$1 and coordinat\$5	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/17 16:13
-	537	((road and window\$1) and gradient\$1 and coordinat\$5) and (accurac\$5 or precision\$5)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/17 16:14
-	676	((road and window\$1) and gradient\$1 and coordinat\$5) and (accurac\$5 or precision\$5 or close\$3 or metric\$3 or match\$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/17 16:14
-	4222	382/100,104;340/907;348/113;701/200,300.ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/18 18:47
-	30	382/100,104;340/907;348/113;701/200,300.ccls. and road and window\$1 and gradient\$1 and coordinates	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/18 18:52
-	9	(382/100,104;340/907;348/113;701/200,300.ccls. and road and window\$1 and gradient\$1 and coordinates) and ((vehicle or car or automobile) near4 lateral)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/18 18:52
-	5684	382/104,107,199,202;404/12,13,16;701/23,28,41; and road	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 07:10
-	1631	382/104,107,199,202;404/12,13,16;701/23,28,41; and road	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/19 19:21
-	309	(382/104,107,199,202;404/12,13,16;701/23,28,41; and road) and ((line or lane) near3 (determin\$ or detect\$4 or calcul\$5))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/19 19:22

-	39	((382/104,107,199,202;404/12,13,16;701/23,28,41) and road) and ((line or lane) near3 (determin\$ or detect\$4 or calcul\$5))) and gradient\$1 and coordinate\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/19 19:32
-	1428	road and ((line or lane) near7 recogni\$8)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/19 19:33
-	15	(road and ((line or lane) near7 recogni\$8)) and ((gradient and coordinate\$1) same (lane or line))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/19 19:52
-	1414	382/100.ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/19 19:52
-	868	382/100.ccls. and (lane or line)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/19 19:53
-	41	(382/100.ccls. and (lane or line)) and road	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/19 19:53
-	5684	382/104,107,199,202;404/12,13,16;701/23,28,41;703/24,25,26,27,28,29,30,31,32,33,34,35,36,37,38,39,40,41,42,43,44,45,46,47,48,49,50,51,52,53,54,55,56,57,58,59,60,61,62,63,64,65,66,67,68,69,70,71,72,73,74,75,76,77,78,79,80,81,82,83,84,85,86,87,88,89,90,91,92,93,94,95,96,97,98,99,100	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 06:47
-	241	382/104,107,199,202;404/12,13,16;701/23,28,41;703/24,25,26,27,28,29,30,31,32,33,34,35,36,37,38,39,40,41,42,43,44,45,46,47,48,49,50,51,52,53,54,55,56,57,58,59,60,61,62,63,64,65,66,67,68,69,70,71,72,73,74,75,76,77,78,79,80,81,82,83,84,85,86,87,88,89,90,91,92,93,94,95,96,97,98,99,100 and (road near4 line)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 07:10
-	5684	382/104,107,199,202;404/12,13,16;701/23,28,41;703/24,25,26,27,28,29,30,31,32,33,34,35,36,37,38,39,40,41,42,43,44,45,46,47,48,49,50,51,52,53,54,55,56,57,58,59,60,61,62,63,64,65,66,67,68,69,70,71,72,73,74,75,76,77,78,79,80,81,82,83,84,85,86,87,88,89,90,91,92,93,94,95,96,97,98,99,100	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 07:11
-	329	382/104,107,199,202;404/12,13,16;701/23,28,41;703/24,25,26,27,28,29,30,31,32,33,34,35,36,37,38,39,40,41,42,43,44,45,46,47,48,49,50,51,52,53,54,55,56,57,58,59,60,61,62,63,64,65,66,67,68,69,70,71,72,73,74,75,76,77,78,79,80,81,82,83,84,85,86,87,88,89,90,91,92,93,94,95,96,97,98,99,100 and (road near3 (lane or line))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 07:18

-	24	(382/104,107,199,202;404/12,13,16;701/23,28,41;USPAT;cls. and (road near3 (lane or line))) and gradient\$1 and coordinate\$1	US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 07:12
-	1	(road near3 (lane or line)) and ((window\$1 or display\$1) near4 (gradient\$1 and coordinate\$1))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 07:21
-	505	((white near2 line\$1) near4 (detect\$5 or recogniz\$6)) and road	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 07:22
-	25	((white near2 line\$1) near4 (detect\$5 or recogniz\$6)) and road) and gradient\$1 and coordinate\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 07:22
-	0	intelligent near3 vehicle\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 07:31
-	26157	automatic near3 driv\$4	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 07:32
-	29971	automatic near3 (driv\$4 or steer\$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 07:32
-	11917	(automatic near3 (driv\$4 or steer\$4)) and (lane or line)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 07:33
-	0	((automatic near3 (driv\$4 or steer\$4)) and (lane or line)) and gradient\$1 and cordinate\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 07:34
-	4845369	o	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 07:34

-	156	((automatic near3 (driv\$4 or steer\$4)) and (lane or line)) and gradient\$1 and coordinate\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 07:34
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2 Image understanding based on edge histogram method for rear-end collision avoidance system
Yamada, K.; Ito, T.;

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3 Road-Boundary Detection and Tracking Using Ladar Sensing
Wijesoma, W.S.; Kodagoda, K.R.S.; Balasuriya, A.P.;

Robotics and Automation, IEEE Transactions on, Volume: 20, Issue: 3, June 2004

Pages:456 - 464

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4 A fast and robust vision based road following algorithm
Aufrere, R.; Chapuis, R.; Chausse, F.;

Intelligent Vehicles Symposium, 2000. IV 2000. Proceedings of the IEEE, 3-5 2000

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5 Results on visual road recognition for road vehicle guidance

Behringer, R.; Maurer, R.B.M.;

Intelligent Vehicles Symposium, 1996., Proceedings of the 1996 IEEE , 19-20 1996

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6 Finding and tracking road lanes using "line-snakes"

Dong Jung Kang; Jang Won Choi; In So Kweon;

Intelligent Vehicles Symposium, 1996., Proceedings of the 1996 IEEE , 19-20 1996

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7 On-board camera 3D-motion analysis

Uchimura, K.; Zhencheng Hu;

Information, Decision and Control, 2002. Final Program and Abstracts , 11-13 2002

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8 Curve finder combining perceptual grouping and a Kalman like fittir

Guichard, F.; Tarel, J.-P.;

Computer Vision, 1999. The Proceedings of the Seventh IEEE International Conference on , Volume: 2 , 20-27 Sept. 1999

Pages:1003 - 1008 vol.2

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9 A robust lane detection using real-time voting processor

Takahashi, A.; Ninomiya, Y.; Ohta, M.; Tange, K.;

Intelligent Transportation Systems, 1999. Proceedings. 1999 IEEE/IEEE/JSAI International Conference on , 5-8 Oct. 1999

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10 Understanding driving situations using a network model

Ito, T.; Yamada, K.; Nishioka, K.;

Intelligent Vehicles '95 Symposium., Proceedings of the , 25-26 Sept. 1995

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Industrial Electronics, 2002. ISIE 2002. Proceedings of the 2002 IEEE International Symposium on, Volume: 2 , 8-11 July 2002

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